

# **RC1500A**

Antenna Controller for Single Axis Antennas



## **FEATURES**

- ➢ Polarization Control Interface Automatic or manual polarization control for three-wire Polarotor<sup>™</sup> or optional control for 24V rotating feeds with potentiometer feedback
- High-Resolution Pulse Sensor Interface Ensures accurate Ku-band positioning
- Software Controlled Limits Provides backup to mechanical limits
- Dual Speed For fast slewing, fine positioning, user programmable

- RS-422 PC Control Interface Automated control with many popular packages; basic PC-control software is Included
- ➤ Adapti-Drive<sup>TM</sup> Maintains stable speed with varying load
- Solid-State Drive Circuitry Provides reliable, quiet operation, rated for 36V at 10A with over-current protection
- Multi-Band Operation Supports C, Ku and L-band satellites

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#### **OPERATIONAL OVERVIEW**

The RC1500 was designed to provide years of reliable operation through the use of a heavy duty solid-state drive network coupled with a novel microcontroller-based fault monitoring system. The 10 amp rated drive output capability is adequate for either moving feed trackers or full-size linear actuators and the Adapti-Drive digital servo speed control optimizes antenna movement for today's demanding Ku-band applications. Additional features like an RS-422 communications port for PC control and a very user-friendly, menu scheme make the RC1500 a unique and highly adaptable piece of equipment. Overall, the RC1500 is well equipped to handle the demanding requirements for cost sensitive domestic and optionally international inclined-orbit satellite tracking.

#### MODES

The RC2000A operates in a mode architecture whereby the controller's operational status is governed by the selected mode. An explanation of these modes are listed below.

MANUAL:	Allows for manual jogging of the	e azimuth and polarization axis.	The fast/slow speed toggle is active in this mode.	

AUTO: A satellite, previously saved in memory, can be recalled and the RC1500A will position the antenna on the selected satellite.

- SETUP: This mode stores values memory for a selected satellite.
- RESET: Used to reset the drive over-current protection circuits after the load error has been corrected.
- DELETE: Allows the user to delete a satellite from the list of stored values.
- FIX: Used to restore the proper position counters in the event of a memory error or sensor failure.
- AZIM SLOW: This mode allows the user to select an appropriate drive slow speed value to optimize system performance.
- CONFIG: Provides a concise point to enter any necessary system constants or enable options.
- LIMITS: Software limits are set for the main axis. This is used as a backup for mechanical limits.

### SPECIFICATIONS

PHYSICAL		DRIVE	
Size:	19.0″ x 3.5″ x 9.0″ (rack)	Output:	36 VDC, 10.0 Amps; 360VA
Weight:	8.5 lbs.	Sensor Input:	Pulse-type: Reed, Hall Effect, Optical
Temperature:	0° – 50° C	Polarization:	Standard Polarotor <sup>TM</sup> Interface,
Input Power:	115/230 VAC, 50/60 Hz., 40 W		optional rotating Feed-drive at voltages from 5 – 36 VDC @ 1A max